

A Numerical Study of Effective Stress and Groundwater Level Changes in Poroelastic Aquifer under Dynamic Excitations

C. Y. Chiu\*, C. L. Wang\*, K. C. Hsu\*, K. C. Chang\*\*

\*Department of Resources Engineering, National Cheng Kung University, Taiwan \*\*Water Resources Agency, Ministry of Economic Affairs, Taiwan

## Introduction





#### Mechanism





## Objectives

- Modified dynamic poroelastic theory
- Numerical study
  - Sensitivity study
  - Effect of boundary condition
  - Stratum layer analysis
  - Case Study
    - Choshui River fan

### The equations...

➡ Poroelasticity: ■ Biot(1941) ■ Rice & Cleary(1976) ■ Roeloffs(1996) ➡ Equations: Law of Geometry Law of Material Constitution Law of Deformation and Flow ⇒ Problem: ■ 2D plane strain

### **Biot's Classical Poroelasticity**

#### **Basic Assumptions**

Isotropy
Reversible process
Linear stress & strain constitution
Infinitesimal deformation
Incompressible fluid
Darcy's flow law

## Biot's original equations

$$G\nabla^{2}u_{x} + \frac{G}{1-2\upsilon}\frac{\partial\varepsilon}{\partial x} - \alpha\frac{\partial p}{\partial x} = \rho\frac{\partial^{2}u_{x}}{\partial t^{2}}$$
$$G\nabla^{2}u_{y} + \frac{G}{1-2\upsilon}\frac{\partial\varepsilon}{\partial y} - \alpha\frac{\partial p}{\partial y} = \rho\frac{\partial^{2}u_{y}}{\partial t^{2}}$$
$$G\nabla^{2}u_{z} + \frac{G}{1-2\upsilon}\frac{\partial\varepsilon}{\partial z} - \alpha\frac{\partial p}{\partial z} = \rho\frac{\partial^{2}u_{z}}{\partial t^{2}}$$
$$\frac{k}{\gamma_{w}}\nabla^{2}p = \alpha\frac{\partial\varepsilon}{\partial t} + \frac{1}{Q}\frac{\partial p}{\partial t}$$

## Law of infinitesimal deformation

The total strain - displacement relations in plane strain :

$$\begin{cases} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \varepsilon_{zz} = 0 \\ \gamma_{xy} \end{cases} = \begin{bmatrix} \frac{\partial}{\partial x} & 0 & 0 \\ 0 & \frac{\partial}{\partial y} & 0 \\ 0 & 0 & \frac{\partial}{\partial z} \\ \frac{\partial}{\partial y} & \frac{\partial}{\partial x} & 0 \end{bmatrix} \begin{cases} u_x \\ u_y \\ u_z = \text{constant} \end{cases}$$

## **HILE** porous materials

For homogeneous isotropic linear elastic porous materials : The total stress - strain relations in plane strain :

$$\begin{cases} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{zz} \\ \tau_{xy} \end{cases} = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} 1-\nu & \nu & \nu & 0 \\ \nu & 1-\nu & \nu & 0 \\ \nu & \nu & 1-\nu & 0 \\ 0 & 0 & 0 & \frac{1-2\nu}{2} \end{bmatrix} \begin{bmatrix} \varepsilon_{xx} \\ \varepsilon_{yy} \\ \varepsilon_{zz} = 0 \\ \gamma_{xy} \end{bmatrix}$$

The effective stress concept :

$$\begin{cases} \sigma_{xx}^{e} \\ \sigma_{yy}^{e} \\ \sigma_{zz}^{e} \\ \tau_{xy} \end{cases} = \begin{cases} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{yy} \\ \sigma_{zz} \\ \tau_{xy} \end{cases} + \alpha \begin{cases} p \\ p \\ p \\ 0 \end{cases}$$

where + stands for tension.

$$\alpha = \frac{3(\nu_u - \nu)}{B(1 + \nu_u)}$$

### Governing law of deformation

The dynamic stress equations:

 $\frac{\partial \sigma^{e}_{xx}}{\partial x} + \frac{\partial \tau^{e}_{xy}}{\partial y} = \rho \frac{\partial^{2} u_{x}}{\partial t^{2}} + \zeta \frac{\partial u_{x}}{\partial t}$  $\frac{\partial \tau^{e}_{yx}}{\partial x} + \frac{\partial \sigma^{e}_{yy}}{\partial y} = \rho \frac{\partial^{2} u_{y}}{\partial t^{2}} + \zeta \frac{\partial u_{y}}{\partial t}$ Damping where Inertia  $\sigma^{e}_{xx}, \sigma^{e}_{yy}, \tau^{e}_{xy} = \text{effective stress components (Pa = N/m^2)},$  $(u_x, u_y)$  = displacement vector (m),  $\rho = \text{mass density}(\text{kg/m}^3),$  $\zeta = \text{damping coefficient}(\text{kg/m}^3\text{s}),$ 

## Governing law of flow



## Formulation

$$V_{x} = \frac{d(u_{x})}{dt}$$

$$V_{z} = \frac{d(u_{z})}{dt}$$

$$\frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \sigma_{xz}}{\partial z} = \rho \frac{\partial^{2} u_{x}}{\partial t^{2}} + \zeta V_{x}$$

$$\frac{\partial \sigma_{xz}}{\partial x} + \frac{\partial \sigma_{zz}}{\partial z} = \rho \frac{\partial^{2} u_{z}}{\partial t^{2}} + \zeta V_{z}$$

$$k \nabla^{2} h = \frac{n \beta_{f}}{\gamma_{w}} \frac{\partial h}{\partial t} + \chi \frac{\partial \varepsilon}{\partial t}$$

$$\frac{V_x}{gT_0} = \frac{\partial \left(\frac{u_x}{gT_0^2}\right)}{\partial \overline{t}}$$
$$\frac{V_z}{gT_0} = \frac{\partial \left(\frac{u_z}{gT_0^2}\right)}{\partial \overline{t}}$$
$$\frac{\partial \left(\frac{\sigma^e_{xx}}{\rho gX_0}\right)}{\partial \overline{x}} + \frac{\partial \left(\frac{\sigma_{zx}}{\rho gZ_0}\right)}{\partial \overline{z}} = \frac{\partial \left(\frac{V_x}{gT_0}\right)}{\partial \overline{t}} + \zeta \frac{V_x}{\rho g}$$
$$\frac{\partial \left(\frac{\sigma_{xz}}{\rho gX_0}\right)}{\partial \overline{x}} + \frac{\partial \left(\frac{\sigma^e_{zz}}{\rho gZ_0}\right)}{\partial \overline{z}} = \frac{\partial \left(\frac{V_z}{gT_0}\right)}{\partial \overline{t}} + \zeta \frac{V_z}{\rho g}$$
$$\frac{\partial \left(\frac{\sigma_{xz}}{\rho gX_0}\right)}{\partial \overline{x}} + \frac{\partial \left(\frac{\sigma^e_{zz}}{\rho gZ_0}\right)}{\partial \overline{z}} = \frac{\partial \left(\frac{V_z}{gT_0}\right)}{\partial \overline{t}} + \zeta \frac{V_z}{\rho g}$$
$$\frac{\partial (\overline{h})}{\partial \overline{x}^2} + A \frac{\partial (\overline{h})}{\partial \overline{z}^2} = B \frac{\partial (\overline{h})}{\partial \overline{t}} + C \frac{\partial (\varepsilon)}{\partial \overline{t}}$$

- $\zeta$ : Damping coefficient
- $\chi$ : Volumetric strain amplifying coefficient

$$A = \frac{X_0^2}{k_{xx}} \frac{k_{zz}}{Z_0^2}, \quad B = \frac{X_0^2}{k_{xx}} \frac{\gamma_w}{QT_0}, \quad C = \frac{X_0^2}{k_{xx}} \frac{\chi}{T_0H_0}$$

#### Excitations

A "stamp like" function is used to simulate the jiggle driving force.

The interval,  $\Delta t$ , is chosen to be a small quantity to simulate the impulse-type force.



## The Numerical Model



# **Basic Input Parameters**

Symbol	Sand	Clay	Unit
v: Poisson ratio	0.25	0.3	—
E: Young's coefficient	1E+8	1E+7	N/m <sup>2</sup> (Pa)
$\rho$ : Density	2100	1870	kg/m <sup>3</sup>
n: Porosity	0.375	0.55	_
$\gamma_{w}$ : Unit weight of water	9810	9810	N/m <sup>3</sup>
<i>K</i> : Hydraulic conductivity	1E-4	1E-6	m/sec
$\beta_f$ : Fluid compressibility	4.4E-10	4.4E-10	m <sup>2</sup> /N (Pa <sup>-1</sup> )
$\zeta$ : Damping coefficient	1E+	kg/m <sup>3</sup> .s	
$\chi$ : Volumetric strain amplifying coefficient	1	_	

## Sensitivity Study

- Hydraulic conductivity
  Young's modulus
  Strain amplification coefficient
  Damping coefficient
- **Complitude of Excitations**

#### Hydraulic Conductivity

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Young's modulus



#### Strain amplification coefficient





Damping coefficient

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**Amplitude of Excitations** 

施加應力Force 大小對總應力之影響

作用力Force 大小對有效應力變化之影響



#### Summary of Parametric Study

Parameters	Total Stress	Effective stress	Coseismic water level	Degree of influence		
Hydraulic conductivity 1		$\downarrow$	1	$\checkmark$	***	
Poisson's ratio	1		$\uparrow$	$\downarrow$		
Young's Modulus	1		$\uparrow$	$\downarrow$	***	
Strain Amplification constant	1	1	$\checkmark$	1	***	
Damping coefficient	1	$\downarrow$	$\downarrow$	$\downarrow$	***	
Excitations	1	$\uparrow$	$\uparrow$	1	***	
Fluid compressibility	1			_	×	
Porosity	$\uparrow$				×	
Total density	$\uparrow$		_		×	

#### The effect of boundary condition

Permeability of boundary Drained boundary Undrained boundary Constraint of boundary Rigid boundary Movable boundary Excitations on the boundary Types of excitations



0.5

坡道式 (ramp)

邊界模式-A5 右側施加應力 0 0.5 1 脈衝式 (stamp) ►t /T0
Imp)
A 按 急 墜 式
(ramp then drop)







#### Stratum Analysis





























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Parameter	Name	Aquifer	Aquitard
Hydrology	Hydraulic conductivity (m/sec)	$k_{xx} = k_{zz} = 1e-4$	$k_{xx} = k_{zz} = 1e-7$
	Fluid compressibility(Pa <sup>-1</sup> )	$\beta_{f} = 4.4e-10$	$\beta_{f} = 4.4e-10$
	Unit weight of fluid(N/m <sup>3</sup> )	$\gamma_{w} = 9810$	$\gamma_{w} = 9810$
Material	Porosity (-)	<b>n</b> =0.375	<b>n</b> =0.55
	Young's modulus (Pa)	E=1e8	E=1e7
	Total Density (kg/m^3)	$\rho$ =2100	$\rho$ =1870
	Poisson's ratio (-)	$\nu$ =0.25	$\nu$ =0.3
Dynamics	Damping constant (Pa.s/m <sup>2</sup> ) Strain amplification (-)	$\zeta = 1e+9$ $\chi = 5$	

Mode A: jiggle1 (0.05<t<0.1),  $\zeta = 1e+9$ Mode B: jiggle1 (0.09<t<0.1),  $\zeta = 1e+9$ Mode C: jiggle1 (0.09<t<0.1),  $\zeta = 1e+8$ 









## Calibration

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分析點	模式A			模式B			模式C		
(水位 觀測站)	觀測值	分析值	修正 係數	觀測值	分析值	修正 係數	觀測值	分析值	修正 係數
海園一	-0.058	0.239	-0.243	-0.058	0.090	-0.648	-0.058	0.317	-0.183
田洋一	0.413	-0.147	-2.814	0.413	-0.138	-3.002	0.413	-0.151	-2.744
芳草一	-0.043	0.438	-0.099	-0.043	0.122	-0.355	-0.043	0.692	-0.063
虎溪一	0.379	1.770	0.214	0.379	-0.046	-8.238	0.379	1.912	0.198
東河一	0.532	-0.715	-0.743	0.532	-0.716	-0.742	0.532	-0.741	-0.717
安南一	-0.229	-0.250	0.917	-0.229	-0.174	1.320	-0.229	-0.257	0.894
田洋二	-0.270	1.164	-0.232	-0.270	0.270	-1.000	-0.270	1.442	-0.187
虎尾二	-0.322	1.697	-0.190	-0.322	0.406	-0.793	-0.322	2.074	-0.155
東河二	-4.773	-1.968	2.425	-4.773	-1.970	2.424	-4.773	-2.010	2.375
虎溪三	0.848	-0.244	-3.468	0.848	-0.244	-3.468	0.848	-0.257	-3.296
田洋三	-0.363	0.521	-0.697	-0.363	0.278	-1.307	-0.363	0.493	-0.737

### Conclusions

- Modified dynamic poroelastic theory
- Numerical study

Sensitivity study

Effect of boundary condition

**Stratum** layer analysis

■ Case Study

# When my students see this picture, happy summer is about over!

